

Kinematic Robot Joint Types

Difficulty: Hard

E B I V K H M K E B L M H G D H B I E G Z U J Y V K H Z R M
T Z J O A R I W O Z K E W O L A T V R L O R T N O C P Y H C
W Y H E E V S N Z W G Y V H G M P S H X A M S H O U L D E R
T H R D Q L K R E N X E B K Q H H C I B P T V P L A C V G C
L P I D C R L R I L S B F R A E N I L R O T B E U F H O Y T
X L A N Z E C H E L K N A U R W O B L E W M N O A B A L A D
S B I B X S J W Y V S O Q G G G K Q H Z G S T K E R I N M U
D Z W G E R A Q Q I M V N E N J B D C O V I C N P N N H P N
L I M H E G A K N I L E Z V A I G F Q V D N D H D E G B P D
X R M O T I O N Y B B Z C Q C X L C K N K A U R Y A M C J W
Y C A J M N D O Z E S N E H X O T P P Z C H I F D H M K D K
T H G E N S O C K E T B O V A O S K U K O C Z S B E L T L L
O T N E G M F L E X T F G I T N A V I O A E R D B C E W Y P
Q V U T A L A P Z R P N Z Z V B I C Z L C M X E D I L S R H
A P N U G M X Q A Y G Z L Q Q A T C D S Q C I D W R S K P A
K Q N L N Y T G S L E U Z B P M V W A F R A N A L P X R C O
T K X O S O T Z E J Y L W P U U N A R L Q J B B Y H K R L G
J F F V E V Z K R F N Q L X T N I O J U E V G J A C N J E S
S D N E Y R G U V L V L R U R E L H C M A G U R A W G P H T
V Y A R Y N X G O C L X J N P L Y Z N G M E R N T W T O G M
D T O V I P Y Y V X V B I Q O T G Y P U B O C O C I A S Z I
S Q N R L Z F B P P C P I K F B P Q V A D H V Q T Y M I F Z
W O A H V Q A W Y L R E W A M L U F B I O E H E K A O Z W B
L E B R Z S X N Y I P S N Y C D Z Z X R G W K I R D T S R H
B B K R T X I X S U E A Y H C T E J U T L H R V D C O I W X
R W F R C D S M J F E Z A W Y L U T N R R F K G N O R D O Q
M B Z V G E A Y P Y X S O Y U T C A A E W H J J E M K W O N
G A L L A T E D E H Z Z X P B W J O T T D U D J F Z M Y O S
S L H A I X V N K U L R G X V N M H C O O T B Y V V B W E P
S L J C Q L F L K G I D B R L B E W H S R R R V B K A F Y G

Find these words:

CYLINDRICAL
REVOLUTE
SHOULDER
SLIDER
LINEAR
JOINT
CHAIN
WRIST
GEAR
BEND

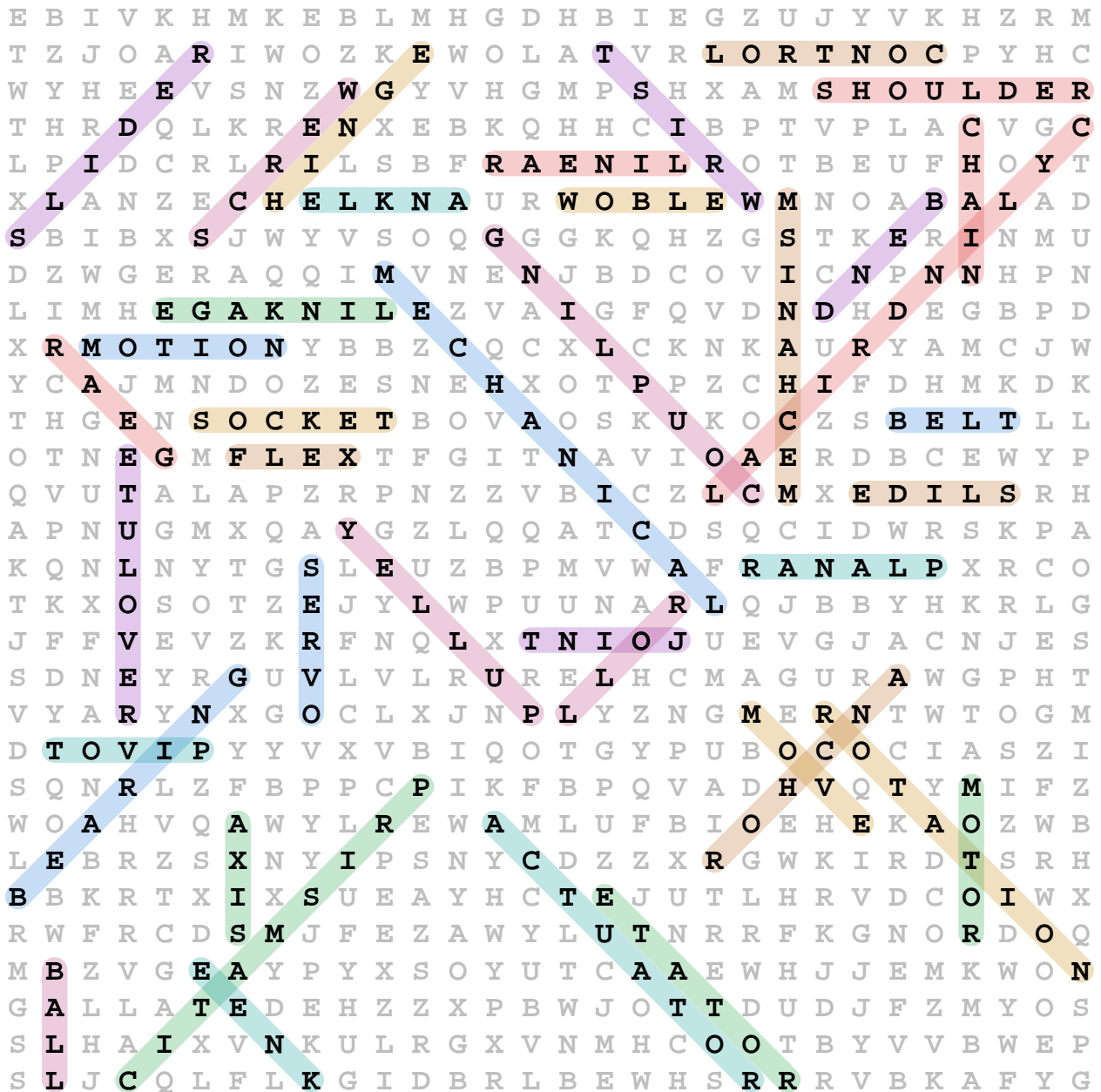
MECHANICAL
ROTATION
BEARING
SOCKET
MOTION
HINGE
SERVO
ELBOW
BELT
MOVE

PRISMATIC
ACTUATOR
LINKAGE
PLANAR
ROTATE
PIVOT
MOTOR
ANKLE
AXIS
KNEE

MECHANISM
COUPLING
CONTROL
PULLEY
ANCHOR
SCREW
SLIDE
BALL
FLEX
ROLL

Kinematic Robot Joint Types - Answer Key

Difficulty: Hard



Words found:

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|-------------|------------|-----------|-----------|
| CYLINDRICAL | MECHANICAL | PRISMATIC | MECHANISM |
| REVOLUTE | ROTATION | ACTUATOR | COUPLING |
| SHOULDER | BEARING | LINKAGE | CONTROL |
| SLIDER | SOCKET | PLANAR | PULLEY |
| LINEAR | MOTION | ROTATE | ANCHOR |
| JOINT | HINGE | PIVOT | SCREW |
| CHAIN | SERVO | MOTOR | SLIDE |
| WRIST | ELBOW | ANKLE | BALL |
| GEAR | BELT | AXIS | FLEX |
| BEND | MOVE | KNEE | ROLL |